

Method for controlling movement of a vehicle with rotary-screw propulsion systems, wherein the steering of the front and rear swivel platforms is controlled such that these platforms can rotate independently of one another in the plane of the road, enabling the vehicle to turn right, left, around its own vertical axis, as well as "sideways" and "crab" movement. When moving on soft ground and water, the rotation of the front and rear rotating platforms is achieved by controlling the thrust and direction of rotation of the rotary-screw propellers, which are installed on both sides of the platforms.